

Solution of Bernoulli Nonlinear Differential Equation through Sadik Transform

Mohd Zafar Saber

*Associate Professor, Department of Mathematics, Kohinoor Arts, Commerce and
Science College Khulatabad 431101, Dist- Chh SambhajiNagar (MS), India*

Email: zafarmaths1@gmail.com

Abstract

In this paper we have solved Bernoulli Differential equation

$$u'(t) + p(t)u(t) = Q(t)u^n(t)$$

for the conditions $p(t) = 0$ and $Q(t) = t^m$, $m \geq 0$ as well as
 $p(t) = t^s$ and $Q(t) = t^m$, $s, m \geq 0$ using Sadik Transform along with
ADM. Sadik transform is now very powerful tool because after applying
the Sadik transform we can have choices whether to proceed through Sadik
transform or by any other integral transform whose kernel is exponential
form just by fixing different values of alpha and beta according to a
convenience and situation of the problem.

Key words: Sadik Transform, Bernoulli Differential equation, ADM.

Introduction

In mathematics, an integral transform maps an equation from its domain into another domain of new variable where it might be converted and solved algebraically and easily than in the original domain. Different Integral transform have been successfully used for two centuries in solving many problems in applied mathematics, mathematical physics, Physical chemistry and engineering science. The solution is back to the original domain using the inverse integral transform. There are so many integral transform are discovered to solve Differential equations, Partial Differential Equations, integral equations etc. which claim their superiority over each other. Recently the Sadik transform has been introduced by Sadikali Latif Shaikh in 2018. The Sadik transform is nothing but generalization of the Laplace Transform, Sumudu Transform, Elzaki Transform, Kamal Transform, Abood Transform, Tarig Transform, Mohand Transform etc. and all those integral transforms whose kernels are of exponential type or similar to the kernel of the Laplace transform.

Preliminaries

In this section, we recall some notions and definitions that will be used through this paper.

Sadik Transform: If $u(t)$ piecewise continuous on the interval $0 \leq t \leq A$ for any $A > 0$, and $|u(t)| \leq K$, where $t \geq M$, for any real and positive constant K and M , then Sadik transform $\mathbb{S}(\nu^\alpha, \beta) = \mathbb{S}[u(t)]$ is defined by

$$\mathbb{S}(\nu^\alpha, \beta) = \mathbb{S}[u(t)] = \frac{1}{\nu^\beta} \int_0^\infty e^{-\nu^\alpha t} u(t) dt$$

where, ν is complex variable, α is any non-zero real numbers, and β is any real number [2].

Properties of Sadik transform

$$\begin{aligned} (1) \quad \mathbb{S}(t^n) &= \frac{\nu^{-\beta} n!}{\nu^{(n+1)\alpha}} & (2) \quad \mathbb{S}(\sin(at)) &= \frac{a\nu^{-\beta}}{\nu^{2\alpha} + a^2} \\ (3) \quad \mathbb{S}(\cos(at)) &= \frac{\nu^\alpha \cdot \nu^{-\beta}}{\nu^{2\alpha} + a^2} & (4) \quad \mathbb{S}(e^{at}) &= \frac{\nu^{-\beta}}{\nu^\alpha - a} \\ (5) \quad \mathbb{S}(\sinh(at)) &= \frac{a\nu^{-\beta}}{\nu^{2\alpha} - a^2} & (6) \quad \mathbb{S}(\cosh(at)) &= \frac{\nu^\alpha \cdot \nu^{-\beta}}{\nu^{2\alpha} - a^2} \end{aligned}$$

Sadik transform on differential coefficients

$$\begin{aligned} \mathbb{S}[x'(t)] &= \nu^\alpha \mathbb{S}(\nu^\alpha, \beta) - \nu^{-\beta} x(0), \\ \mathbb{S}[x^{(n)}(t)] &= \nu^{n\alpha} \mathbb{S}(\nu^\alpha, \beta) - \sum_{k=0}^{n-1} \nu^{k\alpha - \beta} x^{(n-1-k)}(0) \end{aligned}$$

Adomian decomposition method

Adomian decomposition method introduces the solution by decomposing $u(t)$ to an infinite series $u(t) = \sum_{n=0}^\infty u_n(t)$ and the nonlinear term Nu by the infinite series

$N[u(t)] = \sum_{n=0}^\infty A_n$ where A_n are the Adomian polynomials which are generated for each nonlinearity and can be found by the formula

$$A_i = \frac{1}{i!} \left[\frac{d_i}{d\lambda^i} N \left(\sum_{j=0}^\infty \lambda^j u_j \right) \right]_{\lambda=0}, \quad i = 0, 1, 2, \dots$$

Main Result

Theorem 1: Consider Bernoulli differential equation

$$u'(t) + p(t)u(t) = Q(t)u^n(t) \quad (1), \quad \text{with initial condition } u(0) = c$$

where $p(t) = 0$ and $Q(t) = t^m$, $m \geq 0$

Then solution of the above equation is convergence series of

$$u(t) = \sum_{n=0}^{\infty} u_n(t) = u_0(t) + u_1(t) + u_2(t) + \dots \quad \text{where} \quad u_0(t) = c$$

$$u_{k+1}(t) = \mathbb{S}^{-1} \left[\frac{1}{v^\alpha} \mathbb{S} \left[t^m A_k \right] \right] \quad \text{where } A_k \text{ is Adomian polynomial.}$$

Proof: If $p(t) = 0$ and $Q(t) = t^m$, $m \geq 0$ then (1) becomes

$$u'(t) = t^m \cdot u^n(t) \quad (2)$$

here $u^n(t)$ is nonlinear term now by Sadik transform to (2) we get

$$\mathbb{S}(v^\alpha, \beta) = \frac{1}{v^{\alpha+\beta}} c + \frac{1}{v^\alpha} \mathbb{S}(t^m u^n(t)) \quad (3)$$

if we apply inverse Sadik transform we get the solution $u(t)$ but for non-linear part we apply Adomian polynomial method for which we represent solution $u(t)$ by infinite series

$$u(t) = \sum_{i=0}^{\infty} u_i(t) \quad \text{and} \quad u^n(t) = \sum_{i=0}^{\infty} A_i \quad (4)$$

$$\mathbb{S} \left(\sum_{i=0}^{\infty} u_i(t) \right) = \frac{1}{v^{\alpha+\beta}} c + \frac{1}{v^\alpha} \mathbb{S} \left(t^m \sum_{i=0}^{\infty} A_i \right) \quad (5)$$

$$\sum_{i=0}^{\infty} u_i(t) = c + \mathbb{S}^{-1} \left(\frac{1}{v^\alpha} \mathbb{S} \left(t^m \sum_{i=0}^{\infty} A_i \right) \right) \quad (6)$$

$$\therefore u_0(t) = c \quad u_{k+1}(t) = \mathbb{S}^{-1} \left(\frac{1}{v^\alpha} \mathbb{S} (t^m A_k) \right) \quad (7)$$

calculating $u_1(t)$, $u_2(t)$, $u_3(t) \dots$ from (7) we get solution as

$$u(t) = \sum_{n=0}^{\infty} u_n(t) = u_0(t) + u_1(t) + u_2(t) + \dots$$

Example 1. Find solution of Bernoulli nonlinear Differential equation (2) for the different conditions

$$(1) \quad m=1, n=1, \text{ if } u(0) = e$$

$$(2) \quad m=1, n=-1, \text{ if } u(0) = 1$$

$$(3) \quad m=0, n=2, \text{ if } u(0) = 1$$

(1) If $m=1$, $n=1$, if $u(0) = e$ then (2) become

$$u'(t) = t \cdot u(t) \quad (8)$$

applying (7) to (8) where $u(t) = \sum_{i=0}^{\infty} A_i$ we get, $u_0(t) = e$

$$u_{k+1}(t) = \mathbb{S}^{-1} \left[\frac{1}{v^\alpha} \mathbb{S}[t \cdot A_k] \right] \quad (9)$$

using (3) we can find Adomian polynomials as, $A_0 = \frac{1}{0!} [u_0] = u_0 = e$

$$\therefore u_1(t) = \mathbb{S}^{-1} \left[\frac{1}{v^\alpha} \mathbb{S}[t \cdot A_0] \right] = e \mathbb{S}^{-1} \left[\frac{1}{v^{3\alpha+\beta}} \right] = e \frac{t^2}{2!}$$

$$A_1 = \frac{1}{1!} \left[\frac{d}{d\lambda} N(u_0 + \lambda u_1) \right]_{\lambda=0} = \frac{d}{d\lambda} (u_0 + \lambda u_1)$$

$$\therefore u_2(t) = \mathbb{S}^{-1} \left[\frac{1}{v^\alpha} \mathbb{S}[t \cdot A_1] \right] = \frac{e}{2!} \mathbb{S}^{-1} \left[\frac{1}{v^\alpha} \mathbb{S}[t^3] \right] = \frac{e}{2!} \mathbb{S}^{-1} \left[\frac{1}{v^\alpha} \cdot \frac{3!}{v^{4\alpha+\beta}} \right] = \frac{e}{2!} \left(\frac{t^2}{2} \right)^2$$

$$A_2 = \frac{1}{2!} \left[\frac{d^2}{d\lambda^2} N(u_0 + \lambda u_1 + \lambda^2 u_2) \right]_{\lambda=0} = \frac{1}{2!} \left[\frac{d^2}{d\lambda^2} (u_0 + \lambda u_1 + \lambda^2 u_2) \right]_{\lambda=0}$$

$$u_3(t) = \mathbb{S}^{-1} \left[\frac{1}{v^\alpha} \mathbb{S}[t \cdot A_2] \right] = \mathbb{S}^{-1} \left[\frac{1}{v^\alpha} \mathbb{S} \left[t \cdot e \frac{t^4}{8} \right] \right] = \frac{e}{8} \mathbb{S}^{-1} \left[\frac{1}{v^\alpha} \mathbb{S}[t^5] \right] = \frac{e}{3!} \left(\frac{t^2}{2} \right)^3$$

$$\text{similarly } u_n(t) = \frac{e}{n!} \left(\frac{t^2}{2} \right)^n$$

then solution is convergence series $u(t) = \sum_{n=0}^{\infty} u_n(t) = u_0(t) + u_1(t) + u_2(t) + \dots$

$$u(t) = e + e \frac{t^2}{2!} + \frac{e}{2!} \left(\frac{t^2}{2} \right)^2 + \frac{e}{3!} \left(\frac{t^2}{2} \right)^3 + \dots + \frac{e}{n!} \left(\frac{t^2}{2} \right)^n + \dots$$

$$u(t) = e \cdot e^{\frac{t^2}{2}} = e^{\frac{t^2}{2}+1} \quad (10)$$

(2) If $m=1$, $n=-1$, if $u(0)=1$ then (9) become

$$u'(t) = t \cdot [u(t)]^{-1} \quad (11)$$

applying (7) to (8) where $[u(t)]^{-1} = \sum_{i=0}^{\infty} A_i$ we get $u_0(t) = 1 \rightarrow A_0 = 1$

$$u_{k+1}(t) = \mathbb{S}^{-1} \left[\frac{1}{v^\alpha} \mathbb{S}[t \cdot A_k] \right] \quad (12)$$

$$\therefore u_1(t) = \mathbb{S}^{-1} \left[\frac{1}{v^\alpha} \mathbb{S}[t \cdot A_0] \right] = \mathbb{S}^{-1} \left[\frac{1}{v^\alpha} \mathbb{S}(t) \right] = \frac{t^2}{2!}$$

$$A_1 = \frac{1}{1!} \left[\frac{d}{d\lambda} N(u_0 + \lambda u_1) \right]_{\lambda=0} = \frac{d}{d\lambda} (u_0 + \lambda u_1)^{-1} = (-1)(u_0)^{-2} (u_1)$$

$$\therefore u_2(t) = \mathbb{S}^{-1} \left[\frac{1}{v^\alpha} \mathbb{S}[t.A_1] \right] = -\frac{1}{2} \mathbb{S}^{-1} \left[\frac{1}{v^\alpha} \cdot \frac{3!}{v^{4\alpha+\beta}} \right] = -\frac{t^4}{8}$$

$$A_2 = \frac{1}{2!} \left[\frac{d^2}{d\lambda^2} N(u_0 + \lambda u_1 + \lambda^2 u_2) \right]_{\lambda=0} = -\frac{1}{2} \left[-2 \frac{t^4}{4} - \frac{t^4}{4} \right] = \frac{3}{8} t^4$$

$$\therefore u_3(t) = \mathbb{S}^{-1} \left[\frac{1}{v^\alpha} \mathbb{S}[t.A_2] \right] = \frac{3}{8} \mathbb{S}^{-1} \left[\frac{1}{v^\alpha} \cdot \frac{5!}{v^{6\alpha+\beta}} \right] = \frac{t^6}{16}$$

$$\text{similarly} \quad u_4(t) = -\frac{5t^8}{128}, \quad u_5(t) = \frac{7t^{10}}{256}, \dots$$

$$\text{then solution is convergence series} \quad u(t) = \sum_{n=0}^{\infty} u_n(t) = u_0(t) + u_1(t) + u_2(t) + \dots$$

$$\therefore u(t) = \sqrt{1+t^2} \quad (13)$$

(3) If $m=0$, $n=2$, if $u(0)=1$ Bernoulli nonlinear differential equation (2) will be

$$u'(t) = u^2(t) \quad (14)$$

$$\text{applying (7) to (14) where } [u(t)]^2 = \sum_{i=0}^{\infty} A_i \text{ we get } u_0(t)=1 \rightarrow A_0=1$$

$$u_{k+1}(t) = \mathbb{S}^{-1} \left[\frac{1}{v^\alpha} \mathbb{S}[A_k] \right] \quad (15)$$

$$u_1(t) = \mathbb{S}^{-1} \left[\frac{1}{v^\alpha} \mathbb{S}[A_0] \right] = \mathbb{S}^{-1} \left[\frac{1}{v^\alpha} \mathbb{S}[1] \right] = \mathbb{S}^{-1} \left[\frac{1}{v^\alpha} \cdot \frac{1}{v^{\alpha+\beta}} \right] = t$$

$$A_1 = \frac{1}{1!} \left[\frac{d}{d\lambda} N(u_0 + \lambda u_1) \right]_{\lambda=0} = 2u_0 u_1 = 2t$$

$$\therefore u_2(t) = \mathbb{S}^{-1} \left[\frac{1}{v^\alpha} \mathbb{S}[A_1] \right] = \mathbb{S}^{-1} \left[\frac{1}{v^\alpha} \cdot \frac{2}{v^{2\alpha+\beta}} \right] = t^2$$

$$A_2 = \frac{1}{2!} \left[\frac{d^2}{d\lambda^2} (u_0 + \lambda u_1 + \lambda^2 u_2)^2 \right]_{\lambda=0} = \left[(2u_0 u_2) + (u_1)^2 \right] = 3t^2$$

$$\therefore u_3(t) = \mathbb{S}^{-1} \left[\frac{1}{v^\alpha} \mathbb{S}[A_2] \right] = \mathbb{S}^{-1} \left[\frac{1}{v^\alpha} \mathbb{S}[3t^2] \right] = t^3$$

$$\text{Similarly} \quad u_4(t) = t^4, \quad u_5(t) = t^5 \dots$$

$$\text{then solution is convergence series} \quad u(t) = \sum_{n=0}^{\infty} u_n(t) = u_0(t) + u_1(t) + u_2(t) + \dots$$

$$\therefore u(t) = 1 + t + t^2 + t^3 + \dots = \frac{1}{1-t} \quad (16)$$

Theorem: 3.2. Consider Bernoulli differential equation (1)

$$u'(t) + p(t)u(t) = Q(t)u^n(t) \text{ with initial condition } u(0) = c$$

where $p(t) = t^s$ and $Q(t) = t^m$, $s, m \geq 0$ then show that solution of the above

equation is convergence series of $u(t) = \sum_{n=0}^{\infty} u_n(t) = u_0(t) + u_1(t) + u_2(t) + \dots$

where $u_0(t) = c$, $u_{k+1}(t) = \mathbb{S}^{-1} \left[\frac{1}{v^\alpha} \left(\mathbb{S}(t^m A_k) - \mathbb{S}(t^s u_k(t)) \right) \right]$

Proof: If where $p(t) = t^s$ and $Q(t) = t^m$, $s, m \geq 0$ then (1) becomes

$$u'(t) = t^m u^n(t) - t^s u(t) \quad (17)$$

now applying Sadik transform

$$\mathbb{S}(v^\alpha, \beta) = \frac{1}{v^{\alpha+\beta}} c + \frac{1}{v^\alpha} \left(\mathbb{S}(t^m u^n(t)) - \mathbb{S}(t^s u(t)) \right) \quad (18)$$

if we apply inverse Sadik transform we get the solution $u(t)$ but for non-linear part we apply Adomian polynomial method for which we represent solution $u(t)$ by

infinite series $u(t) = \sum_{i=0}^{\infty} u_i(t)$ $u^n(t) = \sum_{i=0}^{\infty} A_i$

$$\mathbb{S} \left[\sum_{i=0}^{\infty} u_i(t) \right] = \frac{1}{v^{\alpha+\beta}} c + \frac{1}{v^\alpha} \left(\mathbb{S} \left(t^m \sum_{i=0}^{\infty} A_i \right) - \mathbb{S} \left(t^p \sum_{i=0}^{\infty} u_i(t) \right) \right)$$

inverse Sadik transform gives

$$\sum_{i=0}^{\infty} u_i(t) = c + \mathbb{S}^{-1} \left[\frac{1}{v^\alpha} \left(\mathbb{S} \left(t^m \sum_{i=0}^{\infty} A_i \right) - \mathbb{S} \left(t^p \sum_{i=0}^{\infty} u_i(t) \right) \right) \right]$$

comparing both sides for $i=0$, and $i=k+1$

$$u_0(t) = c,$$

$$u_{k+1}(t) = \mathbb{S}^{-1} \left[\frac{1}{v^\alpha} \left(\mathbb{S}(t^m A_k) - \mathbb{S}(t^s u_k(t)) \right) \right] \quad (19)$$

Calculating $u_1(t), u_2(t), u_3(t) \dots$ from (19) we get solution by convergence series

$$u(t) = \sum_{n=0}^{\infty} u_n(t) = u_0(t) + u_1(t) + u_2(t) + \dots$$

Example 2. Consider nonlinear differential equation

$$u'(t) + u(t) = t(u(t))^2 \quad (20)$$

with initial condition $u(0)=1$.

Here $p=0$, $m=1$ $\therefore p(t)=1$ and $Q(t)=t$ and $[u(t)]^2 = \sum_{i=0}^{\infty} A_i$

applying Sadik transform from (19) we get,

$$\begin{aligned}
u_0(t) &= A_0 = 1 \\
u_{k+1}(t) &= \mathbb{S}^{-1} \left[\frac{1}{\mathfrak{v}^\alpha} \left(\mathbb{S}(t.A_k) - \mathbb{S}(u_k(t)) \right) \right] \\
\therefore u_1(t) &= \mathbb{S}^{-1} \left[\frac{1}{\mathfrak{v}^\alpha} \left(\mathbb{S}(t.A_0) - \mathbb{S}(u_0(t)) \right) \right] = \frac{t^2}{2} - t \\
A_1 &= \frac{1}{1!} \left[\frac{d}{d\lambda} N(u_0 + \lambda u_1) \right]_{\lambda=0} = t^2 - 2t \\
\therefore u_2(t) &= \mathbb{S}^{-1} \left[\frac{1}{\mathfrak{v}^\alpha} \left(\mathbb{S}(t.A_1) - \mathbb{S}(u_1(t)) \right) \right] = \frac{6t^4}{4!} - \frac{5t^3}{3!} + \frac{t^2}{2!} = \frac{t^4}{4} - \frac{5t^3}{6} + \frac{t^2}{2} \\
A_2 &= \frac{1}{2!} \left[\frac{d^2}{d\lambda^2} (u_0 + \lambda u_1 + \lambda^2 u_2)^2 \right]_{\lambda=0} = \frac{t^4}{2} - \frac{5t^3}{3} + t^2 \\
\therefore u_3(t) &= \mathbb{S}^{-1} \left[\left(\frac{60}{\mathfrak{v}^{7\alpha+\beta}} - \frac{46}{\mathfrak{v}^{6\alpha+\beta}} + \frac{11}{\mathfrak{v}^{5\alpha+\beta}} - \frac{1}{\mathfrak{v}^{4\alpha+\beta}} \right) \right] = \frac{t^6}{12} - \frac{46}{5!} t^5 + \frac{11}{4!} t^4 - \frac{t^3}{3!}
\end{aligned} \tag{21}$$

we get solution by convergence series

$$\begin{aligned}
u(t) &= \sum_{n=0}^{\infty} u_n(t) = u_0(t) + u_1(t) + u_2(t) + \dots \\
\therefore u(t) &= \frac{1}{1+t}
\end{aligned} \tag{22}$$

Conclusions

In this paper we have solved Bernoulli Differential equation for special conditions by Sadik Transform along with ADM. Using different values of α and β we can find solution of $u'(t) = t^m u^n(t)$ (2) by Laplace Transform, Sumudu Transform, Elzaki Transform, Kamal Transform, Abood Transform, Tarig Transform and Mohand Transform etc. combined with ADM, For example $\alpha = -1$, $\beta = -1$, $E\{f(t)\} = T(\mathfrak{v})$ then (7) becomes expression for Elzaki Transform

$$\text{combined with ADM, } \therefore u_0(t) = c \quad \& \quad u_{k+1}(t) = E^{-1} \left[\mathfrak{v} E \left[t^m A_k \right] \right]$$

by applying formulae of Elzaki and ADM then inverse Elzaki formulae we get same solution.

References

- [1] Lokenath Debnath and D, Bhatta, Integral Transform and Their Application, Second Edition, Chapman and Hall/CRC (2006).
- [2] Sadikali Latif Shaikh, Introducing a New Integral Transform: Sadik Transform, American International Journal of Research in Science, Technology, Engineering and Mathematics, 22(1), 100–103 (2018).

- [3] Sadikali latif Shaikh, “Sadik Transform In Control Theory”, International journal of Innovative Sciences and Research Technology, 3, Issue 5,396–398, (2018).
- [4] Shaikh Sadikali and M.S. Chaudhary, On A new Integral Transform and Solution of Some Integral Equations, International Journal of Pure and Applied Mathematics, 73, 299–308, (2011).
- [5] Benaminn C, Kuo, Automatic Control System Prentice Hall of India New Delhi.
- [6] The Electronic Engineering Hand book, 5th Edition McGraw-hill, Section 19, 2005.
- [7] Martine Olivi, The Laplace Transform in Control Theory.
- [8] E.Babolian and J.Biazar; On the order of convergence of Adomian method, Applied Mathematics and Computation, 130 (2) (2002), 383- 387.
- [9] Eman M. A. Hilal and TarigM. Elzaki; Solution of nonlinear partial differential equations by new Laplace variational iteration method, Journal of Function Spaces, vol. 2014, Article ID 790714, 5 pages, 2014.